

Abstract

- Selecting the best regularization parameter in inverse problems is a classical and yet challenging problem.
- We propose and study a statistical machine learning approach based on empirical risk minimization.
- Our main contribution is a theoretical analysis, showing that, provided with enough data, this approach can reach sharp rates.

Model and Approach

Let $A: \mathcal{X} \rightarrow \mathcal{Y}$, \mathcal{X} , \mathcal{Y} Hilbert spaces, be an operator and $x^* \in \mathcal{X}$, $y \in \mathcal{Y}$ be such that

$$y = A(x^*) + \delta, \quad \delta \text{ noise.}$$

To overcome ill-posedness, we consider, for every $\lambda > 0$, the family of regularization methods $X_\lambda = X_\lambda(y)$. A good choice for λ should lead to a good reconstruction:

$$X_\lambda(y) \sim x^*.$$

Question: How to formalize this?

Data-driven approach

1. We turn from deterministic to stochastic inverse problems:

$$Y = A(X) + \delta,$$

where Y , X and δ are random variables.

2. We assume to have pairs $(y_i, x_i) \sim (Y, X)$, $i = 1, \dots, n$, and we find a minimizer of the **empirical risk**:

$$\hat{\lambda}_\Lambda \in \arg \min_{\lambda \in \Lambda} \hat{L}(X_\lambda) := \frac{1}{n} \sum_{i=1}^n \ell(x_i, X_\lambda(y_i)),$$

for a certain bounded discrepancy ℓ , bounded by $M > 0$, and a set of candidates $\Lambda = \{\lambda_1, \dots, \lambda_N\}$, $N \in \mathbb{N}$.

3. Compute an upper bound for $L(X_{\hat{\lambda}_\Lambda})$, where

$$\lambda_\Lambda \in \arg \min_{\lambda \in \Lambda} L(X_\lambda) := \mathbb{E}[\ell(X, X_\lambda)].$$

Assumptions and main result

Assumption 1 We assume that $\mathbb{E}[\delta|X] = 0$ and, moreover, that there exists $\tau > 0$ such that

$$\mathbb{E}[\|\delta\|_{\mathcal{Y}}^2 | X] \leq \tau^2.$$

Assumption 2 We assume, for every $\lambda > 0$, that

$$L(X_\lambda) \leq \varepsilon(\lambda).$$

where ε attains its minimum in λ_* , and there exists $C = C(q)$ such that, for all $q > 1$,

$$\varepsilon(q\lambda) \leq C(q)\varepsilon(\lambda).$$

Assumption 3 Assume $\Lambda = \{\lambda_j = \lambda_1 Q^{j-1}, j = 1, \dots, N\}$, $Q > 1$, with

$$\lambda_1 \leq \lambda_* \leq \lambda_N.$$

Theorem 1 Let Assumptions 1, 2 and 3 be satisfied and let $\eta \in (0, 1]$. Then, with probability at least $1 - \eta$,

$$L(X_{\hat{\lambda}_\Lambda}) \lesssim C(Q)\varepsilon(\lambda_*) + \frac{M}{n} \log \frac{2N}{\eta},$$

where the r.h.s goes to 0 as $n \rightarrow \infty$ (up to a constant).

Idea: Combine

$$L(X_{\hat{\lambda}_\Lambda}) \lesssim 2L(X_{\lambda_*}) + \frac{M}{n} \log \frac{2N}{\eta}$$

and

$$L(X_{\lambda_*}) \leq L(X_{q\lambda_*}) \leq \varepsilon(q\lambda_*) \leq C(Q)\varepsilon(\lambda_*).$$

Spectral Regularization Methods

Consider

$$X_\lambda = g_\lambda(A^*A)A^*Y$$

where A is linear and g_λ , $\lambda > 0$, are spectral functions (e.g. Tikhonov, Landweber, TSVD). Choose $\ell(X, X_\lambda) = \|X_\lambda - X\|^2$. Then,

Theorem 2 There exist constants α , C_1 , $C_2 > 0$ such that

$$\varepsilon(\lambda) = \frac{C_1^2 \tau^2}{\lambda} + C_2^2 \lambda^{2\alpha}.$$

“Nonlinear” Tikhonov Regularization

We consider, for every $\lambda > 0$ and a certain initialization variable X_0 ,

$$X_\lambda = \arg \min_{x \in \mathcal{X}} \|A(x) - Y\|^2 + \lambda \|x - X_0\|^2,$$

where A is non-linear. Choose $\ell(X, X_\lambda) = \|X_\lambda - X\|^2$. Then,

Theorem 3 There exist constants c_1 , $c_2 > 0$ such that

$$\varepsilon(\lambda) = c_1 \frac{(\tau^2 + c_2 \lambda)(1 + \lambda)}{\lambda}.$$

Sparsity Inducing Regularizers

We finally consider, for every $\lambda > 0$,

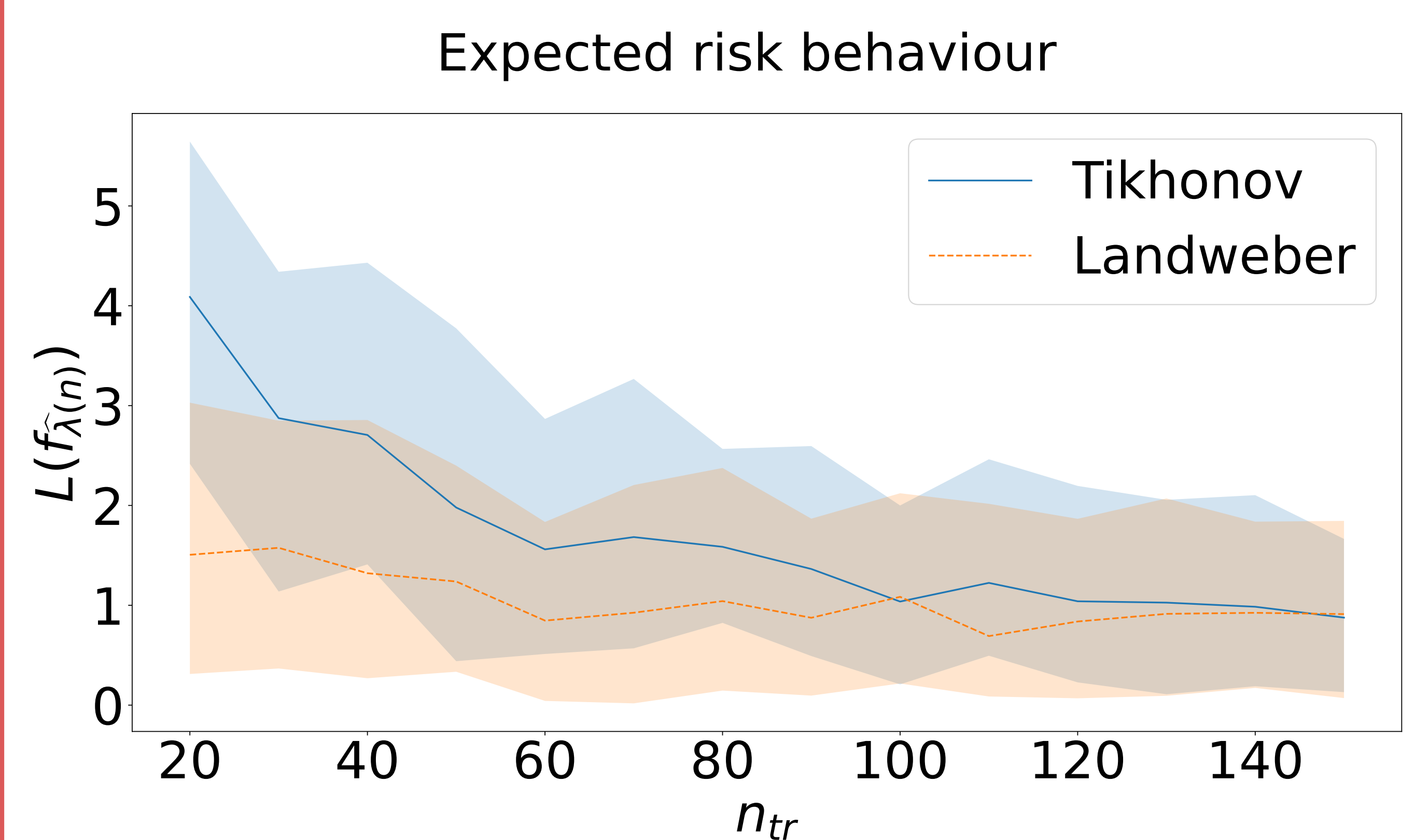
$$X_\lambda = \arg \min_{x \in \mathbb{R}^d} \|Ax - Y\|^2 + \|Gx\|_1$$

where A is linear and $G: \mathbb{R}^d \rightarrow \mathbb{R}^n$ is linear and bounded. Choose $\ell(X, X_\lambda) = D_J(X, X_\lambda)$ the Bregman divergence. Then,

Theorem 4 There exists a constant $c > 0$ such that

$$\varepsilon(\lambda) = \frac{\tau^2 \lambda}{2} + \frac{c^2}{2\lambda}.$$

Expected risk behaviour



We plot here the expected risk w.r.t. $\hat{\lambda}(n)$ for both Tikhonov regularization and the Landweber iteration with $\tau = 0.1$. The solid lines represent the mean value, while the shaded areas are the 1-percentiles and 99-percentiles over 30 trials.

References

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- [3] Arridge, S., Maass, P., Öktem, O., and Schönlieb, C-B.. *Solving inverse problems using data-driven models*. 2019.